

Building High Throughput Permissioned Blockchain Fabrics: Challenges and Opportunities



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About Us

Exploratory Systems Lab at UC Davis

Goal: High-performance resilient data processing.

- 1 Professor, 1 Postdoc, 3 Ph.D. students, 6 M.Sc. and B.Sc. students.
- Recent papers at VLDB, ICDCS, ICDT, DISC, EDBT, and more.
- Intersection of blockchain and database technology.
- ResilientDB: A pioneering new data platform.

Goal: High-performance resilient data processing

Questions

- 1. Why?
- 2. What is the relation with blockchains?
- 3. What do we already have?
- 4. Where can we improve?
- 5. What new tools do we need?





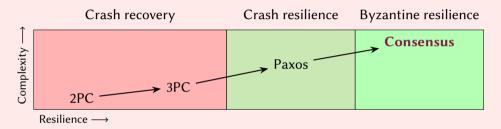
Towards high-performance resilient data processing:

Why?



Why resilient data processing?

Go beyond assumptions of traditional transaction processing!



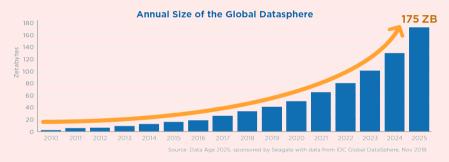
Example

- Provide continuous services during failures.
- Provide services in federated environments.



Why high-performance?

Support requirements of future applications!



- Ever-growing volumes of data (e.g., sensor networks).
- Ever-growing demands of applications (e.g., machine learning).

Towards high-performance resilient data processing:

What is the relation with blockchains?

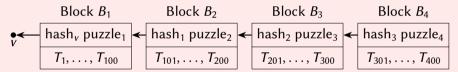
What is a blockchain?



What is a blockchain?

Bitcoin: Management of monetary tokens (Bitcoins)

- ▶ Open and decentralized transfer of tokens (*transactions*).
- History of transactions (*ledger*) stored in the blockchain.



- Many participants hold a copy of the blockchain.
- Blockchain structure is *tamper-proof* by design.

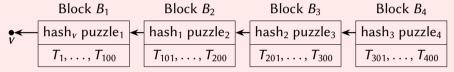




What is a blockchain? - Malicious behavior

Bitcoin: Preventing malicious behavior

► Malicious attempts to change a chain.



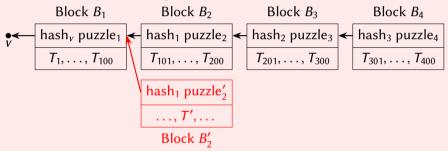




What is a blockchain? - Malicious behavior

Bitcoin: Preventing malicious behavior

► Malicious attempts to change a chain.



- Longest chain has highest incentives.
- Making blocks (solving puzzles) is very costly.
- ► Malicious attempt leads to a *dead end*.





What is a blockchain? - A definition

A resilient tamper-proof ledger maintained by many participants.

- ► Ledger. Append-only sequence of transactions. In database terms: a journal or log.
- Resilient. High availability via full replication among participants.
- ► *Tamper-proof*. Changes can only be made with majority participation.

Blockchains are distributed fully-replicated systems!





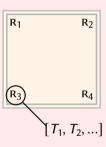
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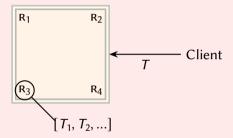
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- 2. Holding the ledger of transactions.







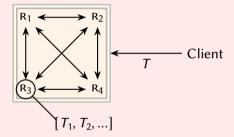
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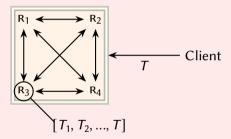
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- 4. Transaction agreement via consensus.







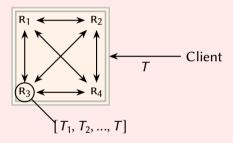
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- 1. Replicas.
- 2. Holding the ledger of transactions.
- 3. Clients with new transactions.
- 4. Transaction agreement via consensus.
- 5. Append-only updates to ledger.
- 6. Cryptography.







Bitcoin: A permissionless blockchain

The participants are not known and can change.

Rationale: Fully decentralized and open cryptocurrencies

- Bitcoin, Ethereum,
- Scale to thousands of participants.
- ► Low transaction processing throughput.
- Very high transaction latencies.





We focus on permissioned blockchains

All participants are known.

Rationale: Data processing in managed environment

- Support different attack models than cryptocurrencies.
- Easier to support low latencies and high throughputs.
- Downside: changing participants is hard.

Many ideas also apply to permissionless blockchains.





Towards high-performance resilient data processing:

What do we already have?





We have consensus: PBFT, PAXOS, PoW, ...

Termination Each non-faulty replica decides on a transaction.

Non-divergence Non-faulty replicas decide on the same transaction.





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Response Clients learn about the outcome of their requests.

Service Every client will be able to request transactions.





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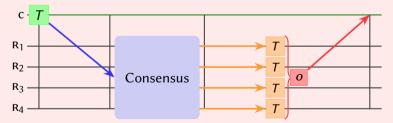
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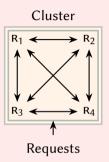
Service Every client will be able to request transactions.



Operating a fully-replicated ledger using consensus

Each replica maintains a copy of the ledger: Append-only sequence of transactions.

- 1. Use consensus to select the ρ -th client request T.
- 2. Append T as the ρ -th entry to the ledger.
- 3. Execute T as the ρ -th entry, inform client.



Consistent state: Linearizable order and deterministic execution On identical inputs, execution of transactions at all non-faulty replicas must produce identical outputs.





Variations on consensus: Byzantine Broadcast (Generals)

Assume a replica G is the general and holds transaction T.

A *Byzantine broadcast algorithm* is an algorithm satisfying:

Termination Each non-faulty replica decides on a transaction.

Non-divergence Non-faulty replicas decide on the same transaction.

Dependence If the general G is non-faulty, then non-faulty replicas will decide on *T*.



(T' = T if the general G is non-faulty).

Variations on consensus: Interactive consistency

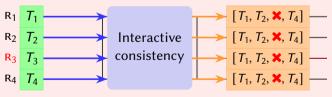
Assume **n** replicas and each replica R_i holds a transaction T_i .

An *interactive consistency algorithm* is an algorithm satisfying:

Termination Each non-faulty replica decides on **n** transactions.

Non-divergence Non-faulty replicas decide on the same transactions.

Dependence If replica R_j is non-faulty, then non-faulty replicas will decide on T_j .



Distributed fully-replicated systems: The CAP Theorem

Consistency Does every participant have exactly the same data?

Availability Does the system continuously provide services?

Partitioning Can the system cope with network disturbances?

Theorem (The CAP Theorem)

Can provide at most two-out-of-three of these properties.





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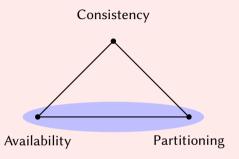
Can provide at most two-out-of-three of these properties.

CAP Theorem uses narrow definitions!





The CAP Theorem and Blockchains



Permissionless Blockchains

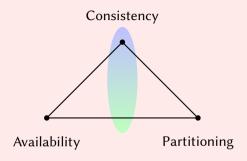
Open membership focuses on Availability and Partitioning.

 \implies Consistency not guaranteed (e.g., forks).





The CAP Theorem and Blockchains



Permissioned Blockchains

Consistency at all costs.

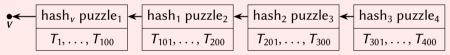
- ⇒ Availability when communication is reliable.
- \implies Some network failure when replicas are reliable.





What else do we have?

- ▶ A lot of *theory* on consensus: consensus is costly.
- PBFT: A practical Byzantine fault-tolerant consensus protocol.
- ► Tamper-proof *ledgers*.



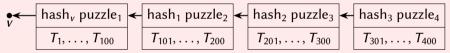
Exact details: depend on consensus, application, attack model, ...

► Many cryptographic tools.



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Exact details: depend on consensus, application, attack model, ...

► Many cryptographic tools.

What about high-performance?



Theory on consensus: Summary

Limitations of practical consensus

- ► No asynchronous communication!
- Dealing with f malicious failures requires n > 3f replicas.
- ▶ Worst-case: at least Ω (**f** + 1) phases of communication.
- Worst-case: at least Ω (**nf**) signatures and Ω (**n** + **f**²) messages.
- Network must stay connected when removing 2f replicas.

Consensus in practice

Asynchronous communication, $\mathbf{n} > 3\mathbf{f}$, clique network:

⇒ termination only when communication is reliable.





Towards high-performance resilient data processing:

What do we already have?

PBFT

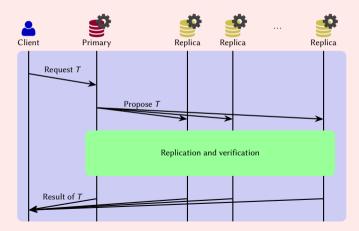




Рвгт: Practical Byzantine Fault Tolerance

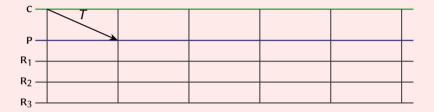
Primary Coordinates consensus: propose transactions to replicate.

Backup Accept transactions and verifies behavior of primary.





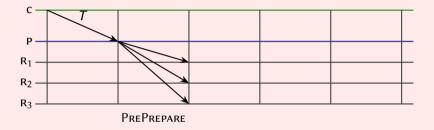
Рвгт: Normal-case protocol in view *v*



 $\langle T \rangle_{\rm c}$.



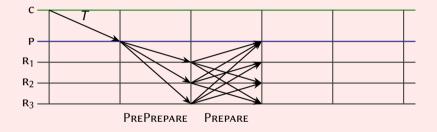
Рв τ : Normal-case protocol in view v



Prepare $(\langle T \rangle_c, v, \rho)$.



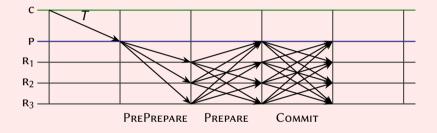
Рвгт: Normal-case protocol in view *v*



If receive PrePrepare message m: Prepare (m).



Рвгт: Normal-case protocol in view *v*

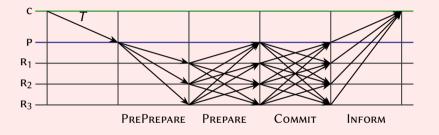


If $\mathbf{n} - \mathbf{f}$ identical PREPARE(m) messages: Commit(m).





PBFT: Normal-case protocol in view *v*



If $\mathbf{n} - \mathbf{f}$ identical Commit(m) messages: execute, Inform($\langle T \rangle_c, \rho, r$).





PBFT: Normal-case consensus

Theorem

If the primary is non-faulty and communication is reliable, then the normal-case of PBFT ensures consensus on T in round ρ .

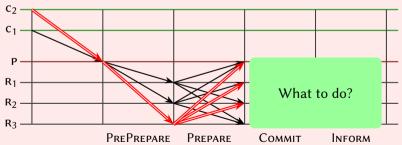


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Example (Byzantine primary, $\mathbf{n} = 4$, $\mathbf{f} = 1$, $\mathbf{n} - \mathbf{f} = 3$)



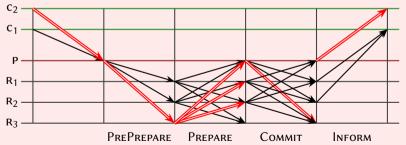


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Theorem (Castro et al.) If replicas R_i , $i \in \{1, 2\}$, commit to $m_i = \text{PrePrepare}(\langle T_i \rangle_{c_i}, v, \rho)$, then $\langle T_1 \rangle_{c_1} = \langle T_2 \rangle_{c_2}$.



PBFT: A normal-case property when n > 3f

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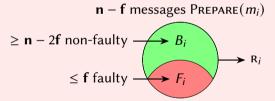


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Proof.

$$\mathbf{n} - \mathbf{f}$$
 messages $\mathsf{PREPARE}(m_i)$

$$\geq \mathbf{n} - 2\mathbf{f} \text{ non-faulty} \qquad \qquad \mathbf{B}_i$$

$$\leq \mathbf{f} \text{ faulty} \qquad \qquad \mathbf{F}_i$$

If
$$\langle T_1 \rangle_{c_1} \neq \langle T_2 \rangle_{c_2}$$
, then $B_1 \cap B_2 = \emptyset$ and $|B_1 \cup B_2| \geq 2(\mathbf{n} - 2\mathbf{f})$.





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$$2(\textbf{n}-2\textbf{f}) \leq \textbf{n}-\textbf{f}$$







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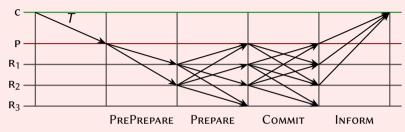
$$2(n-2f) \le n-f$$
 iff $2n-4f \le n-f$ iff $n \le 3f$.





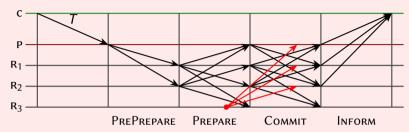


Primary P is faulty ignores R₃



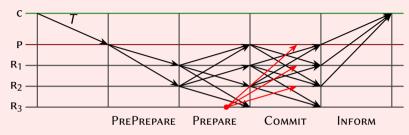


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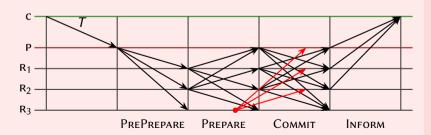




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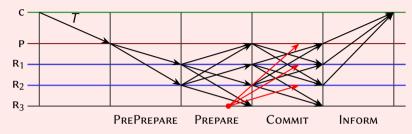


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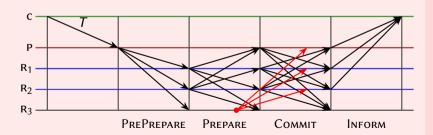




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PBFT: Detectable primary failures

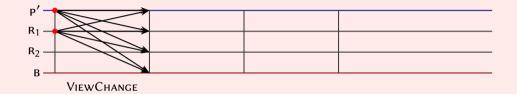
If the primary behaves faulty to $> \mathbf{f}$ non-faulty replicas, then failure of the primary is detectable.

Replacing the primary: View-change at replica R

- 1. R detects *failure* of the current primary P.
- 2. R chooses a new primary P' (the next replica).
- 3. R provides P' with its *current state*.
- 4. P' proposes a new view.
- 5. If the new view is valid, then R switches to this view.

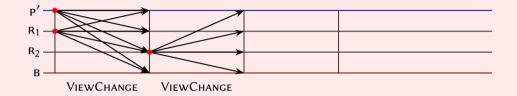






Send VIEWCHANGE(E, v) with E all prepared transactions.

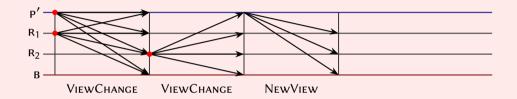




Indirect failure detection by R_2 .





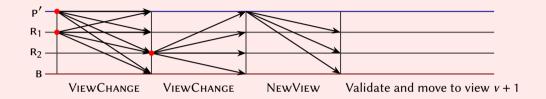


If $\mathbf{n} - \mathbf{f}$ valid ViewChange(E, v) messages: NewView($v + 1, \mathcal{E}, \mathcal{N}$).

- \triangleright \mathcal{E} contains $\mathbf{n} \mathbf{f}$ valid ViewChange messages.
- ▶ N contains no-op proposals for *missing rounds*.







Move to view v + 1 if NewView $(v + 1, \mathcal{E}, \mathcal{N})$ is valid.

- \triangleright \mathcal{E} contains $\mathbf{n} \mathbf{f}$ valid ViewChange messages.
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Рвгт: A property of view-changes when n > 3f

Theorem (Castro et al.)

Let $NewView(v', \mathcal{E}, \mathcal{N})$ be a well-formed NewView message. If a set S of $\mathbf{n}-2\mathbf{f}$ non-faulty replicas committed to m in view v< v', then \mathcal{E} contains a ViewChange message preparing m.



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Proof.

The ViewChange messages in \mathcal{E} :

$$\mathbf{n} - \mathbf{f}$$
 messages ViewChange $(E, v' - 1)$
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 $\leq \mathbf{f}$ faulty



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if $S \cap B = \emptyset$, then $|S \cup B| \ge 2(\mathbf{n} - 2\mathbf{f})$, a contradiction!



Рвгт: Further dealing with failures

Undetected failures: e.g., ignored replicas.
 At least n - 2f > f non-faulty replicas participate: checkpoints.



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- 3. View-change cost: includes all previous transactions! Checkpoints: view-change includes *last successful* checkpoint.



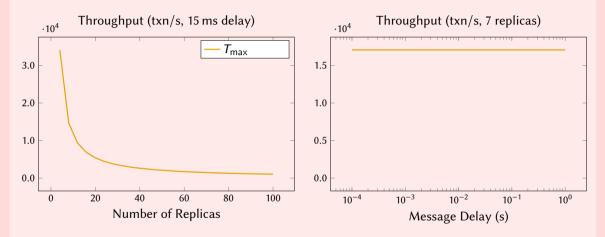


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- 2. Detected failures: primary replacement. Worst-case: a sequence of \mathbf{f} view-changes ($\Omega(\mathbf{f})$ phases).
- 3. View-change cost: includes all previous transactions! Checkpoints: view-change includes *last successful* checkpoint.
- 4. Unreliable communication: replacement of non-faulty primaries. Worst-case: replacements until communication becomes *reliable*.







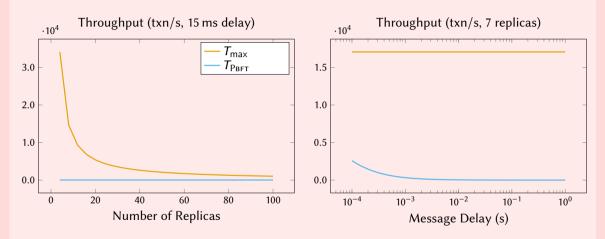
(Maximum throughput of any primary-backup broadcast protocol)

¹Bandwidth: 100 MiB/s, PrePrepare message size: 1024 B, Prepare and Commit message size: 256 B.









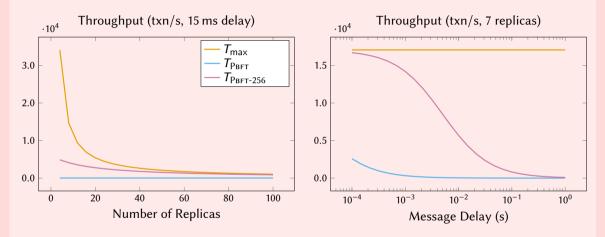
(Maximum throughput of in-order Рвгт)

¹Bandwidth: 100 MiB/s, PrePrepare message size: 1024 B, Prepare and Commit message size: 256 B.







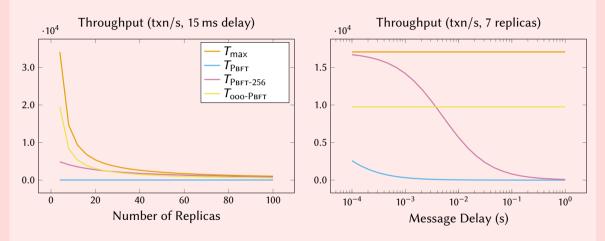


(Maximum throughput of in-order PBFT with batching, 256 txn/batch)





¹Bandwidth: 100 MiB/s, PrePrepare message size: 1024 B, Prepare and Commit message size: 256 B.



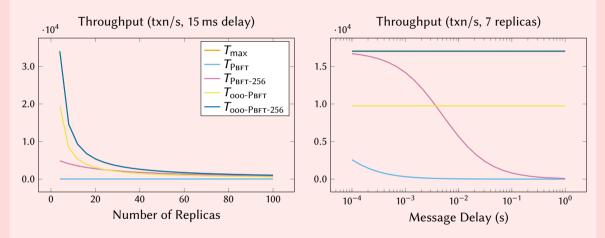
(Maximum throughput of out-of-order Рвгт)

¹Bandwidth: 100 MiB/s, PrePrepare message size: 1024 B, Prepare and Commit message size: 256 B.









(Maximum throughput of out-of-order PBFT with batching, 256 txn/batch)

¹Bandwidth: 100 MiB/s, PrePrepare message size: 1024 B, Prepare and Commit message size: 256 B.







Towards high-performance resilient data processing:

Where can we improve?





A look at high-performance data processing

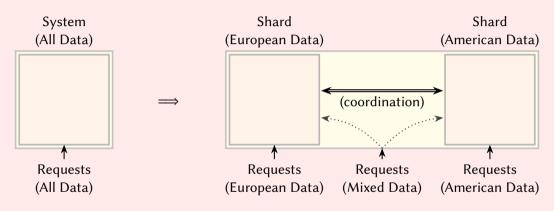
Scalability: adding resources \Longrightarrow *adding performance.*

Full replication: adding resources (replicas) ⇒ less performance!



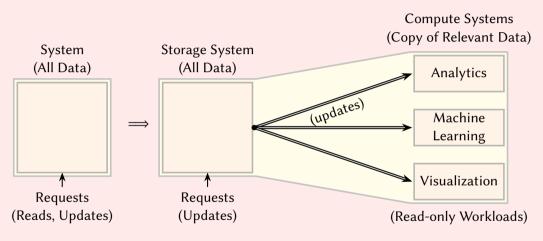


Sharding and Geo-scale aware sharding



Adding shards \Longrightarrow adding throughput (parallel processing), adding storage.

Role Specialization: Read-only workloads



Specializing roles \Longrightarrow adding throughput (parallel processing, specialized hardware, ...).

Towards high-performance resilient data processing:

What new tools do we need?





Central ideas for improvement

Reminder

We can make a resilient cluster that manages data: *blockchains*.

- ▶ **Sharding**: make each shard an independent blockchain. Requires: reliable communication between blockchains. Permissionless blockchains: relays, atomic swaps!
- ▶ **Role Specialization**: make the storage system a blockchain. Requires: reliable read-only updates of the blockchain. Permissionless blockchains: light clients!

Consensus is of no use here if we want efficiency.





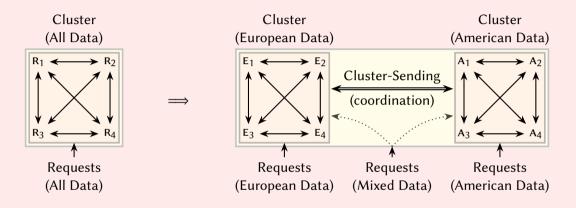
Towards high-performance resilient data processing:

What new tools do we need? Sharding





Sharding: Reliable communication between blockchains



The Byzantine cluster-sending problem.

The Byzantine cluster-sending problem

The problem of sending a value v from a cluster C_1 to a cluster C_2 such that

- ightharpoonup all non-faulty replicas in C_2 RECEIVE the value v;
- \triangleright all non-faulty replicas in C_1 confirm that the value v was received; and
- \triangleright C_2 only receives a value v if all non-faulty replicas in C_1 AGREE upon sending v.

Requirements to provide reliable communication between clusters with Byzantine replicas.





Global communication versus local communication

Straightforward cluster-sending solution (crash failures) Pair-wise broadcasting with $(\mathbf{f}_1 + 1)(\mathbf{f}_2 + 1) \approx \mathbf{f}_1 \times \mathbf{f}_2$ messages.



Global communication versus local communication

Straightforward cluster-sending solution (crash failures) Pair-wise broadcasting with $(\mathbf{f}_1 + 1)(\mathbf{f}_2 + 1) \approx \mathbf{f}_1 \times \mathbf{f}_2$ messages.

	Ping round-trip times (ms)						Bandwidth (Mbit/s)					
	OR	ΙA	Mont.	BE	TW	Syd.	OR	IA	Mont.	BE	TW	Syd.
Oregon	≤ 1	38	65	136	118	161	7998	669	371	194	188	136
Iowa		≤ 1	33	98	153	172		10004	752	243	144	120
Montreal			≤ 1	82	186	202			7977	283	111	102
Belgium				≤ 1	252	270				9728	79	66
Taiwan					≤ 1	137					7998	160
Sydney						≤ 1						7977

$$\mathbf{n}_1 = 15
 \mathbf{n}_2 = 5
 \mathbf{f}_1 = 7
 \mathbf{f}_2 = 2$$

Claim (crash failures)



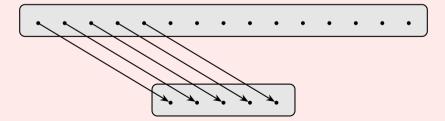






$$\mathbf{n}_1 = 15
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Claim (crash failures)

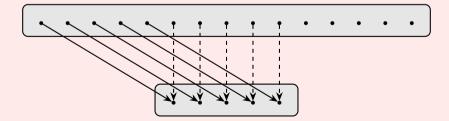






$$\mathbf{n}_1 = 15 \\
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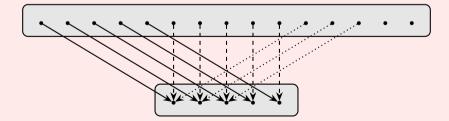






$$\mathbf{n}_1 = 15
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Claim (crash failures)

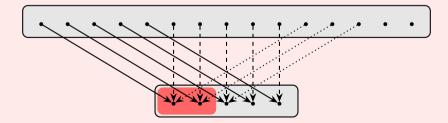






$$\mathbf{n}_1 = 15
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Claim (crash failures)

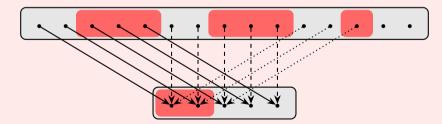






$$\mathbf{n}_1 = 15
 \mathbf{n}_2 = 5
 \mathbf{f}_1 = 7
 \mathbf{f}_2 = 2$$

Claim (crash failures)







Lower bounds for cluster-sending: Results

Theorem (Cluster-sending lower bound, simplified)

We need to exchange $max(\mathbf{n}_1, \mathbf{n}_2)$ messages to do cluster-sending.

Theorem (Cluster-sending lower bound, crash failures)

Assume $\mathbf{n}_1 \geq \mathbf{n}_2$ and let

$$q = (\mathbf{f}_1 + 1) \operatorname{div} \mathbf{nf}_2;$$
 $r = (\mathbf{f}_1 + 1) \operatorname{mod} \mathbf{nf}_2.$

We need to exchange at least $q\mathbf{n}_2 + r + \mathbf{f}_2 \operatorname{sgn} r \approx \mathbf{n}_1$ messages to do cluster-sending.





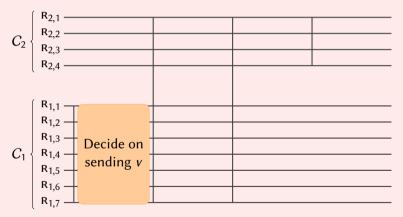
An optimal cluster-sending algorithm (crash failures)

Protocol for the sending cluster C_1 , $n_1 \ge n_2$, $n_1 \ge \sigma$:

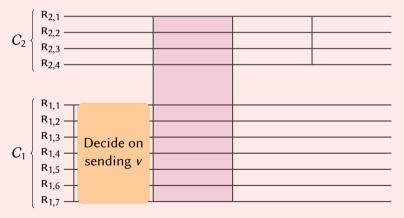
- 1: *AGREE* on sending v to C_2 .
- 2: Choose replicas $\mathcal{P} \subseteq C_1$ with $|\mathcal{P}| = \sigma$.
- 3: Choose a \mathbf{n}_2 -partition partition(\mathcal{P}) of \mathcal{P} .
- 4: **for** $P \in partition(\mathcal{P})$ **do**
- 5: Choose replicas $Q \subseteq C_2$ with |Q| = |P|.
- 6: Choose a bijection $b: P \rightarrow Q$.
- 7: **for** $R_1 \in P$ **do**
- 8: Send v from R_1 to $b(R_1)$.

Protocol for the receiving cluster C_2 :

- 9: **event** $R_2 \in C_2$ receives w from a replica in C_1 **do**
- 10: Broadcast w to all replicas in C_2 .
- 11: **event** $R_2 \in C_2$ receives w from a replica in C_2 **do**
- 12: R₂ considers *w RECEIVED*.

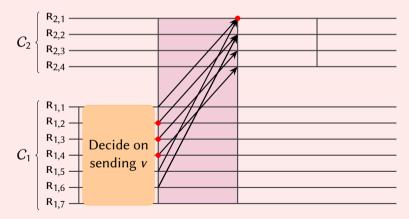




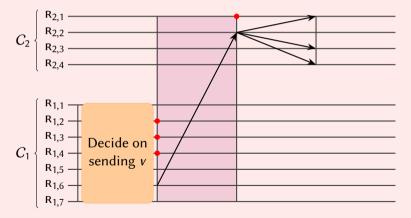




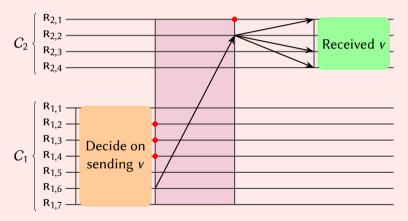
















Cluster-sending: Can we do better

Pessimistic

No: these protocols are worst-case optimal.

Cannot do better than *linear communication* in the size of the clusters.





Cluster-sending: Can we do better

Pessimistic

No: these protocols are worst-case optimal.

Cannot do better than *linear communication* in the size of the clusters.

Optimistic—upcoming results

Yes: if we randomly choose sender and receiver, then we often do much better! Probabilistic approach: expected-case only *constant communication* (four steps).





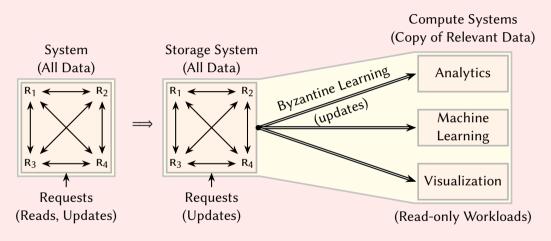
Towards high-performance resilient data processing:

What new tools do we need?

Role Specialization



Role Specialization: Reliable read-only updates of the blockchain



The Byzantine learner problem.

The Byzantine learner problem

The problem of sending a ledger \mathcal{L} maintained by a cluster C to a learner L such that:

- ▶ the learner L will eventually RECEIVE ALL transactions in \mathcal{L} ; and
- \blacktriangleright the learner L will *ONLY RECEIVE* transactions in \mathcal{L} .

Practical requirements

- ► Minimizing overall communication.
- Load balancing among all replicas in C.





Background: Information dispersal algorithms

Definition

Let v be a value with storage size s = ||v||.

An *information dispersal algorithm* can encode v in \mathbf{n} pieces v' such that v can be *decoded* from every set of $\mathbf{n} - \mathbf{f}$ such pieces.

Theorem (Rabin 1989)

The IDA algorithm is an optimal information dispersal algorithm:

- ► Each piece v' has size $\left[\frac{\|v\|}{\mathbf{n}-\mathbf{f}}\right]$.
- ► The $\mathbf{n} \mathbf{f}$ pieces necessary for decoding have a total size of $(\mathbf{n} \mathbf{f}) \left\lceil \frac{\|v\|}{(\mathbf{n} \mathbf{f})} \right\rceil \approx \|v\|$.





The delayed-replication algorithm

Idea: C sends a ledger $\mathcal L$ to learner L

- 1. Partition the ledger \mathcal{L} in sequences S of \mathbf{n} transactions.
- 2. Replica $R_i \in C$ encodes S into the i-th IDA piece S_i .
- 3. Replica $R_i \in C$ sends S_i with a checksum $C_i(S)$ of S to learner L.
- 4. Learner \bot receives at least $\mathbf{n} \mathbf{f}$ distinct and valid pieces and decodes S.

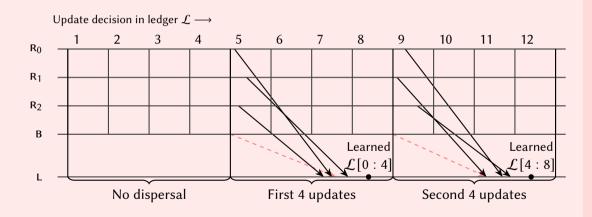
Observation (n > 2f)

- ► Replica R_i sends at most $B = \left\lceil \frac{\|S\|}{n-f} \right\rceil + c \leq \frac{2\|S\|}{n} + 1 + c = O\left(\frac{\|S\|}{n} + c\right)$ bytes.
- ▶ Learner L receives at most $\mathbf{n} \cdot B = O(\|S\| + c\mathbf{n})$ bytes.



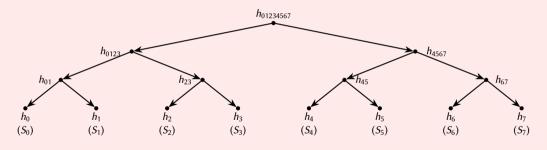


Communication by the delayed-replication algorithm





Consider 8 replicas and a sequence *S*. We construct the checksum $C_5(S)$ of S (used by R_5).

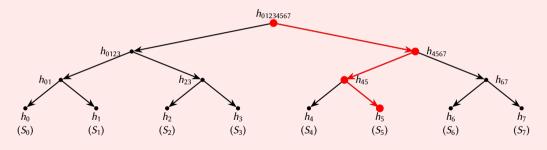


Construct a Merkle tree for pieces S_0, \ldots, S_7 .





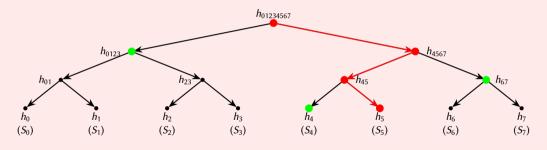
Consider 8 replicas and a sequence *S*. We construct the checksum $C_5(S)$ of S (used by R_5).



Determine the path from root to S_5 .



Consider 8 replicas and a sequence *S*. We construct the checksum $C_5(S)$ of S (used by R_5).

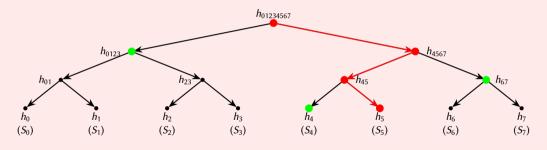


Select *root* and *neighbors*: $C_5(S) = [h_4, h_{67}, h_{0123}, h_{01234567}].$





Consider 8 replicas and a sequence S. We construct the checksum $C_5(S)$ of S (used by R_5).



If one knows the root: *validity* of individual pieces can be determined.



Delayed-replication: Main result (n > 2f)

Theorem

Consider the learner L, replica $R \in C$, and ledger \mathcal{L} .

The delayed-replication algorithm with tree checksums guarantees

- 1. L will learn \mathcal{L} ;
- 2. L will receive at most $|\mathcal{L}|$ messages with a total size of $O(||\mathcal{L}|| + |\mathcal{L}| \log n)$;
- 3. L will only need at most $|\mathcal{L}|/\mathbf{n}$ decode steps;
- 4. R will sent at most $|\mathcal{L}|/n$ messages to L of size $O\left(\frac{\|\mathcal{L}\|+|\mathcal{L}|\log n}{n}\right)$.

Adding replicas to cluster $C \Longrightarrow$ less communication per replica!



Application: Scalable storage for resilient systems

- \triangleright Clusters typically need a *view* $\mathcal V$ on the data to decide whether updates are valid.
- \triangleright Clusters only need the full ledger \mathcal{L} for recovery.
- ▶ We can use *delayed-replication* to reduce the data each replica has to store.

Theorem

The storage cost per replica can be reduced from

$$O\left(\|\mathcal{L}\| + \|\mathcal{V}\|\right)$$
 to $O\left(\frac{\|\mathcal{L}\|}{\mathsf{n} - \mathsf{f}} + \frac{|\mathcal{L}|}{\mathsf{n}}\log(\mathsf{n}) + \|\mathcal{V}\|\right)$.





Towards high-performance resilient data processing:

Concluding remarks





Conclusion

We need an extensive toolbox!

Consensus

Cross-blockchain communication

Read-only participation

(permissioned)

(permissionless)

PBFT, Paxos, ... Cluster-sending PoW, PoS, ...

Relays, atomic swaps

Byzantine learning Light clients

High-performance resilient data processing is nearby.





Ongoing work

Initial results are available

- ► Cluster-sending: DISC 2019, doi: 10.4230/LIPIcs.DISC.2019.45.
- Byzantine learning: ICDT 2020, doi: 10.4230/LIPIcs.ICDT.2020.17.
- Geo-aware consensus: VLDB 2020, doi: 10.14778/3380750.3380757.

More about us and our work

► Jelle Hellings https://ihellings.nl/.

https://expolab.org/.

https://resilientdb.com/.







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